Operating Systems Lecture 12

Readers/Writers and Deadlock

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Goals for Today



- Readers/Writers Lock
- Deadlock

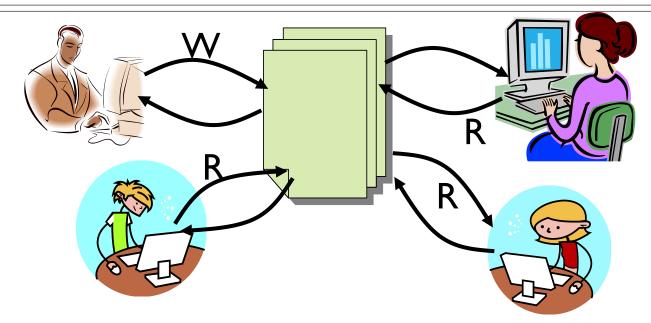
Goals for Today



- Readers/Writers Lock
- Deadlock

Readers/Writers Problem





- Motivation: Consider a shared database
 - Two classes of users:
 - □Readers never modify database
 - □Writers read and modify database
 - Is using a single lock on the whole database sufficient?
 - Like to have many readers at the same time
 - Only one writer at a time



Basic Readers/Writers Solution

- Correctness Constraints:
 - Readers can access database when no writers
 - Writers can access database when no readers or writers
 - Only one thread manipulates state variables at a time
- Basic structure of a solution:

```
- Reader()
     Wait until no writers
     Access data base
     Check out - wake up a waiting writer
- Writer()
     Wait until no active readers or writers
     Access database
     Check out - wake up waiting readers or writer
- State variables (Protected by a lock called "lock"):
    \Box int AR: Number of active readers; initially = 0
    \Box int WR: Number of waiting readers; initially = 0
    \Box int AW: Number of active writers; initially = 0
    \Box int WW: Number of waiting writers; initially = 0
    □ Condition okToRead = NIL
    □Condition okToWrite = NIL
```

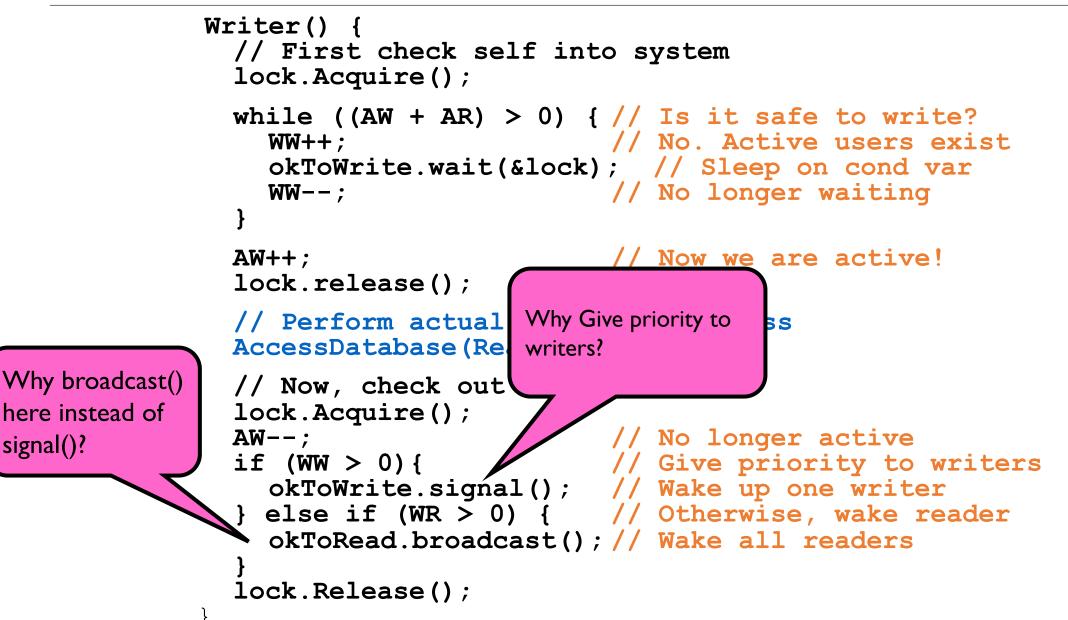
Code for a Reader



```
Reader() {
               // First check self into system
               lock.Acquire();
               while ((AW + WW) > 0) { // Is it safe to read?
                 WR++;
                                        // No. Writers exist
                 okToRead.wait(&lock); // Sleep on cond var
                 WR--;
                                        // No longer waiting
Why release lock
                }
here?
                                        // Now we are active!
               AR++;
               lock.release();
               // Perform actual read-only access
               AccessDatabase(ReadOnly);
               // Now, check out of system
               lock.Acquire();
               AR--;
                                        // No longer active
               if (AR == 0 && WW > 0) // No other active readers
                  okToWrite.signal(); // Wake up one writer
               lock.Release();
```

Code for a Writer





signal()?



- Use an example to simulate the solution
- Consider the following sequence of operators:
 R1, R2, W1, R3
- Initially: AR = 0, WR = 0, AW = 0, WW = 0

- R1 comes along
- AR = 0, WR = 0, AW = 0, WW = 0

```
Reader()
   lock.Acquire(
    while ((AW + WW) > 0) \{ // \text{ Is it safe to read} \}
      WR++;
                                 No. Writers exist
      okToRead.wait(&lock); // Sleep on cond var
                                 No longer waiting
      WR - -;
    AR++;
                              // Now we are active!
    lock.release();
    AccessDbase(ReadOnly);
    lock.Acquire();
    AR - -;
    if (AR == 0 \& WW > 0)
      okToWrite.signal();
    lock.Release();
```

- R1 comes along
- AR = 0, WR = 0, AW = 0, WW = 0

```
Reader()
    lock.Acquire();
                                Is it safe to read?
    while
      WR++;
                                No. Writers exist
      okToRead.wait(&lock); // Sleep on cond var
                                No longer waiting
      WR - -;
                              // Now we are active!
    AR++;
    lock.release();
    AccessDbase(ReadOnly);
    lock.Acquire();
   AR - -;
    if (AR == 0 \& WW > 0)
      okToWrite.signal();
    lock.Release();
```

- R1 comes along
- AR = 1, WR = 0, AW = 0, WW = 0

```
Reader()
    lock.Acquire();
    while ((AW + WW) > 0) \{ // \text{ Is it safe to read} \}
      WR++;
                                 // No. Writers exist
      okToRead.wait(&lock); // Sleep on cond var
WR--; // No longer waiting
    AR++;
                                 // Now we are active!
    lock.release();
    AccessDbase(ReadOnly);
    lock.Acquire();
    AR - -;
    if (AR == 0 \& WW > 0)
       okToWrite.signal();
    lock.Release();
```

- R1 comes along
- AR = 1, WR = 0, AW = 0, WW = 0

```
AccessDbase(ReadOnly);
```

```
lock.Acquire();
AR--;
if (AR == 0 && WW > 0)
    okToWrite.signal();
lock.Release();
```

- R1 comes along
- AR = 1, WR = 0, AW = 0, WW = 0

AccessDbase(ReadOnly)

```
lock.Acquire();
AR--;
if (AR == 0 && WW > 0)
    okToWrite.signal();
lock.Release();
```

- R2 comes along
- AR = 1, WR = 0, AW = 0, WW = 0

```
Reader()
   lock.Acquire(
   while ((AW + WW) > 0) \{ //
                                Is it safe to read?
      WR++;
                                No. Writers exist
      okToRead.wait(&lock); // Sleep on cond var
                                No longer waiting
      WR - -;
   AR++;
                             // Now we are active!
    lock.release();
   AccessDbase(ReadOnly);
    lock.Acquire();
   AR - -;
    if (AR == 0 \& WW > 0)
      okToWrite.signal();
    lock.Release();
```

- R2 comes along
- AR = 1, WR = 0, AW = 0, WW = 0

```
Reader()
    lock.Acquire();
                                Is it safe to read?
    while
      WR++;
                                No. Writers exist
      okToRead.wait(&lock); // Sleep on cond var
                                No longer waiting
      WR - -;
                              // Now we are active!
    AR++;
    lock.release();
    AccessDbase(ReadOnly);
    lock.Acquire();
   AR - -;
    if (AR == 0 \& WW > 0)
      okToWrite.signal();
    lock.Release();
```

- R2 comes along
- AR = 2, WR = 0, AW = 0, WW = 0

```
Reader()
    lock.Acquire();
    while ((AW + WW) > 0) \{ // \text{ Is it safe to read} \}
      WR++;
                                 // No. Writers exist
      okToRead.wait(&lock); // Sleep on cond var
WR--; // No longer waiting
                                 // Now we are active!
    AR++;
    lock.release();
    AccessDbase(ReadOnly);
    lock.Acquire();
    AR - -;
    if (AR == 0 \& WW > 0)
       okToWrite.signal();
    lock.Release();
```

- R2 comes along
- AR = 2, WR = 0, AW = 0, WW = 0

```
AccessDbase(ReadOnly);
```

```
lock.Acquire();
AR--;
if (AR == 0 && WW > 0)
    okToWrite.signal();
lock.Release();
```

- R2 comes along
- AR = 2, WR = 0, AW = 0, WW = 0

```
Reader()
    lock.Acquire();
    while ((AW + WW) > 0) \{ // \text{ Is it safe to read} \}
       WR++;
                                 // No. Writers exist
      okToRead.wait(&lock); // Sleep on cond var
WR--; // No longer waiting
                                 // Now we are active!
    AR++;
    lock.release();
    AccessDbase(ReadOnly)
    lock.Acquire();
    AR - -;
    if (AR == 0 \& WW > 0)
       okToWrite signal():
     Assume readers take a while to access database
  }
         Situation: Locks released, only AR is non-zero
```

- W1 comes along (R1 and R2 are still accessing dbase)
- AR = 2, WR = 0, AW = 0, WW = 0

```
Writer()
      lock.Acquire()
      while ((AW + AR) > 0) { // Is it safe to write?
WW++;
okToWrite.wait(&lock);// No. Active users exist
WW--;
WW--;
      AW++;
      lock.release();
      AccessDbase(ReadWrite);
      lock.Acquire();
      AW-
if
            (\dot{W}W > 0)
         okToWrite.signal();
else if (WR > 0) {
  okToRead.broadcast();
       lock.Release();
```

- W1 comes along (R1 and R2 are still accessing dbase)
- AR = 2, WR = 0, AW = 0, WW = 0

```
Writer()
      lock.Acquire();
                ((AW + AR)
         ile ((AW + AR) > 0) { // Is it safe to write?
WW++;
okToWrite.wait(&lock);// Sleep on cond var
WW--;
// No longer waiting
      while
      AW++;
      lock.release();
      AccessDbase(ReadWrite);
      lock.Acquire();
      AW-
if
            (\dot{W}W > 0)
         okToWrite.signal();
else if (WR > 0) {
  okToRead.broadcast();
       lock.Release();
```

- W1 comes along (R1 and R2 are still accessing dbase)
- AR = 2, WR = 0, AW = 0, WW = 1

```
Writer()
      lock.Acquire();
      while ((AW + AR) > 0) { // Is it safe to write?
    WW++;
    okToWrite.wait(&lock);// No. Active users exist
    WW--;
      AW++;
      lock.release();
      AccessDbase(ReadWrite);
      lock.Acquire();
      AW-
if
            (\dot{W}W > 0)
         okToWrite.signal();
else if (WR > 0) {
  okToRead.broadcast();
       lock.Release();
```

- W1 comes along (R1 and R2 are still accessing dbase)
- AR = 2, WR = 0, AW = 0, WW = 1

```
Writer()
      lock.Acquire();
     while ((AW + AR) > 0) { // Is it safe to write?
    WW++;
    okToWrite.wait(&lock); // No. Active users exist
    WW--;
      AW++;
      lock.release();
      AccessDbase(ReadWrite);
      lock.Acquire();
      AW-
if
            (\dot{W}W > 0)
         okToWrite.signal();
else if (WR > 0) {
  okToRead.broadcast();
      lock.Release();
      W1 cannot start because of readers, so goes to sleep
```

- R3 comes along (R1, R2 accessing dbase, W1 waiting)
- AR = 2, WR = 0, AW = 0, WW = 1

```
Reader()
   lock.Acquire(
   while ((AW + WW) > 0) {
                                Is it safe to read?
      WR++;
                                No. Writers exist
      okToRead.wait(&lock); // Sleep on cond var
                                No longer waiting
      WR - -;
                             // Now we are active!
   AR++;
    lock.release();
   AccessDbase(ReadOnly);
    lock.Acquire();
   AR - -;
    if (AR == 0 \& WW > 0)
      okToWrite.signal();
    lock.Release();
```

- R3 comes along (R1, R2 accessing dbase, W1 waiting)
- AR = 2, WR = 0, AW = 0, WW = 1

```
Reader()
    lock.Acquire();
                                Is it safe to read?
    while
      WR++;
                                No. Writers exist
                             // Sleep on cond var
      okToRead.wait(&lock);
                                No longer waiting
      WR--;
   AR++;
                             // Now we are active!
    lock.release();
   AccessDbase(ReadOnly);
    lock.Acquire();
   AR - -;
    if (AR == 0 \& WW > 0)
      okToWrite.signal();
    lock.Release();
```

- R3 comes along (R1, R2 accessing dbase, W1 waiting)
- AR = 2, WR = 1, AW = 0, WW = 1

```
Reader()
    lock.Acquire();
    while ((AW + WW) > 0) \{ // \text{ Is it safe to read} \}
      WR++;
                                 No. Writers exist
      okToRead.wait(&lock); // Sleep on cond var
                                 No longer waiting
      WR - -;
                              // Now we are active!
    AR++;
    lock.release();
    AccessDbase(ReadOnly);
    lock.Acquire();
    AR - -;
    if (AR == 0 \& WW > 0)
      okToWrite.signal();
    lock.Release();
```

- R3 comes along (R1, R2 accessing dbase, W1 waiting)
- AR = 2, WR = 1, AW = 0, WW = 1

```
Reader()
     lock.Acquire();
     while ((AW + WW) > 0) \{ // \text{ Is it safe to read} \}
                                  No. Writers exist
       WR++;
       okToRead.wait(&lock); // Sleep on cond var
                                   No longer waiting
       WR--;
                                // Now we are active!
     AR++;
     lock.release();
     AccessDbase(ReadOnly);
     lock.Acquire();
     AR--;
Status:

    R1 and R2 still reading

  W1 and R3 waiting on okToWrite and okToRead, respectively
```

- R2 finishes (R1 accessing dbase, W1, R3 waiting)
- AR = 2, WR = 1, AW = 0, WW = 1

```
Reader()
    lock.Acquire();
    while ((AW + WW) > 0) \{ // \text{ Is it safe to read} \}
      WR++;
                                 // No. Writers exist
      okToRead.wait(&lock); // Sleep on cond var
WR--; // No longer waiting
                                 // Now we are active!
    AR++;
    lock.release();
    AccessDbase(ReadOnly);
    lock.Acquire();
    AK--;
    if (AR == 0 \& WW > 0)
       okToWrite.signal();
    lock.Release();
```

- R2 finishes (R1 accessing dbase, W1, R3 waiting)
- AR = 1, WR = 1, AW = 0, WW = 1

```
Reader()
    lock.Acquire();
    while ((AW + WW) > 0) \{ // \text{ Is it safe to read} \}
      WR++;
                                 // No. Writers exist
      okToRead.wait(&lock); // Sleep on cond var
WR--; // No longer waiting
                                 // Now we are active!
    AR++;
    lock.release();
    AccessDbase(ReadOnly);
    lock Acquire():
    AR--:
    if (AR == 0 \& WW > 0)
       okToWrite.signal();
    lock.Release();
```

- R2 finishes (R1 accessing dbase, W1, R3 waiting)
- AR = 1, WR = 1, AW = 0, WW = 1

```
Reader()
    lock.Acquire();
    while ((AW + WW) > 0) \{ // \text{ Is it safe to read} \}
       WR++;
                                 // No. Writers exist
      okToRead.wait(&lock); // Sleep on cond var
WR--; // No longer waiting
    AR++;
                                 // Now we are active!
    lock.release();
    AccessDbase(ReadOnly);
    lock.Acquire();
    AR--;
       (AR == 0 \&\& WW
       okToWrite.signal();
    lock.Release();
```

- R2 finishes (R1 accessing dbase, W1, R3 waiting)
- AR = 1, WR = 1, AW = 0, WW = 1

```
Reader()
    lock.Acquire();
    while ((AW + WW) > 0) \{ // \text{ Is it safe to read} \}
       WR++;
                                 // No. Writers exist
      okToRead.wait(&lock); // Sleep on cond var
WR--; // No longer waiting
                                 // Now we are active!
    AR++;
    lock.release();
    AccessDbase(ReadOnly);
    lock.Acquire();
    AR - -;
    if (AR == 0 \& WW > 0)
       okToWrite.signal();
    lock.Release();
```

- R1 finishes (W1, R3 waiting)
- AR = 1, WR = 1, AW = 0, WW = 1

```
Reader()
    lock.Acquire();
    while ((AW + WW) > 0) \{ // \text{ Is it safe to read} \}
      WR++;
                                 // No. Writers exist
      okToRead.wait(&lock); // Sleep on cond var
WR--; // No longer waiting
    AR++;
                                 // Now we are active!
    lock.release();
    AccessDbase(ReadOnly);
    lock.Acquire();
    AK--;
    if (AR == 0 \& WW > 0)
       okToWrite.signal();
    lock.Release();
```

- R1 finishes (W1, R3 waiting)
- AR = 0, WR = 1, AW = 0, WW = 1

```
Reader()
    lock.Acquire();
    while ((AW + WW) > 0) \{ // \text{ Is it safe to read} \}
      WR++;
                                 // No. Writers exist
      okToRead.wait(&lock); // Sleep on cond var
WR--; // No longer waiting
    AR++;
                                 // Now we are active!
    lock.release();
    AccessDbase(ReadOnly);
    lock Acquire():
    AR--:
    if (AR == 0 \& WW > 0)
       okToWrite.signal();
    lock.Release();
```

- R1 finishes (W1, R3 waiting)
- AR = 0, WR = 1, AW = 0, WW = 1

```
Reader()
    lock.Acquire();
    while ((AW + WW) > 0) \{ // \text{ Is it safe to read} \}
      WR++;
                                 // No. Writers exist
      okToRead.wait(&lock); // Sleep on cond var
WR--; // No longer waiting
    AR++;
                                 // Now we are active!
    lock.release();
    AccessDbase(ReadOnly);
    lock.Acquire();
    AR--;
    if (AR == 0 && WW
       okToWrite.signal();
    lock.Release();
```

- R1 finishes (W1, R3 waiting)
- AR = 0, WR = 1, AW = 0, WW = 1

```
Reader()
    lock.Acquire();
    while ((AW + WW) > 0) \{ // \text{ Is it safe to read} \}
       WR++;
                                 // No. Writers exist
       okToRead.wait(&lock); // Sleep on cond var
WR--: // No longer waiting
                                 // Now we are active!
    AR++;
    lock.release();
    AccessDbase(ReadOnly);
    lock.Acquire();
    AR - -;
    if (AR == 0 \&\& WW > 0)
       okToWrite.signal();
    lock.Release();
   All reader finished, signal writer – note, R3 still waiting
```

- W1 gets signal (R3 still waiting)
- AR = 0, WR = 1, AW = 0, WW = 1

```
Writer()
           lock.Acquire();
           while ((AW + AR) > 0) { // Is it safe to write?
        WW++;
        okToWrite.wait(&lock); // No. Active users exist
        Sleep on cond var
        WW--;
        WW--;
Got signal
                ;
;k.release();
from R1
           AccessDbase(ReadWrite);
           lock.Acquire();
           AW--
if (
                  (\dot{W}W > 0)
               okToWrite.signal();
else if (WR > 0) {
  okToRead.broadcast();
            lock.Release();
```

- W1 gets signal (R3 still waiting)
- AR = 0, WR = 1, AW = 0, WW = 0

```
Writer()
      lock.Acquire();
      while ((AW + AR) > 0) {
                                                 Is it safe to write?
No. Active users exist
Sleep on cond var
No longer waiting
         WW++;
okToWrite.wait(&lock);
         WW--;
      AW++;
      lock.release();
      AccessDbase(ReadWrite);
      lock.Acquire();
      AW-
if
           (\dot{W}W > 0)
         okToWrite.signal();
else if (WR > 0) {
  okToRead.broadcast();
      lock.Release();
```

- W1 gets signal (R3 still waiting)
- AR = 0, WR = 1, AW = 1, WW = 0

```
Writer() {
    lock.Acquire();
    while ((AW + AR) > 0) { // Is it safe to write?
        WW++;
        okToWrite.wait(&lock); // Sleep on cond var
        WW--;
    }
    AW++;
    lock.release();
    AccessDbase(ReadWrite);
    lock.Acquire();
```

```
AW--;

if (WW > 0) {

okToWrite.signal();

} else if (WR > 0) {

okToRead.broadcast();

}

lock.Release();

}
```

- W1 gets signal (R3 still waiting)
- AR = 0, WR = 1, AW = 1, WW = 0

```
Writer()
      lock.Acquire();
      while ((AW + AR) > 0) { // Is it safe to write?
WW++;
okToWrite.wait(&lock);// No. Active users exist
WW--;
WW--;
      AW++;
      lock.release();
      AccessDbase(ReadWrite)
      lock.Acquire();
      AW - -;
if (\underline{W}W > 0) {
         okToWrite.signal();
else if (WR > 0) {
okToRead.broadcast();
       1ock.Release();
```

- W1 gets signal (R3 still waiting)
- AR = 0, WR = 1, AW = 0, WW = 0

```
Writer()
       lock.Acquire();
      while ((AW + AR) > 0) { // Is it safe to write?
    WW++;
    okToWrite.wait(&lock);// No. Active users exist
    WW--;
    WW--;
      AW++;
       lock.release();
      AccessDbase(ReadWrite);
       lock.Acquire();
          (WW > 0) {
  okToWrite.signal();
  else if (WR > 0) {
   okToRead.broadcast();

       lock.Release();
```

- W1 gets signal (R3 still waiting)
- AR = 0, WR = 1, AW = 0, WW = 0

```
Writer()
      lock.Acquire();
     while ((AW + AR) > 0) { // Is it safe to write?
WW++;
okToWrite.wait(&lock);// No. Active users exist
WW--;
WW--;
      AW++;
      lock.release();
      AccessDbase(ReadWrite);
      lock.Acquire();
      \Delta W - -
         okToWrite.signal();
else if (WR > 0) {
  okToRead.broadcast();
      lock.Release();
```

- W1 gets signal (R3 still waiting)
- AR = 0, WR = 1, AW = 0, WW = 0

```
Writer()
      lock.Acquire();
     while ((AW + AR) > 0) { // Is it safe to write?
WW++;
okToWrite.wait(&lock);// No. Active users exist
WW--;
WW--;
      AW++;
      lock.release();
      AccessDbase(ReadWrite);
      lock.Acquire();
      AW--
if (
           (\dot{W}W > 0)
        okToWrite.signal();
else if (WR > 0) {
okToRead.broadcast()
      lock.Release();
      No waiting writer, signal reader R3
```

- R1 finishes (W1, R3 waiting)
- AR = 0, WR = 1, AW = 0, WW = 0

```
AccessDbase(ReadOnly);
```

```
lock.Acquire();
AR--;
if (AR == 0 && WW > 0)
        okToWrite.signal();
lock.Release();
```

- R1 finishes (W1, R3 waiting)
- AR = 0, WR = 0, AW = 0, WW = 0

```
Reader()
    lock.Acquire();
    while ((AW + WW) > 0) \{ // \text{ Is it safe to read} \}
      WR++;
                              // No. Writers exist
      okToRead.wait(&lock); // Sleep on cond var
                              // No longer waiting
      WK--;
                              // Now we are active!
    AR++;
    lock.release();
    AccessDbase(ReadOnly);
    lock.Acquire();
    AR - -;
    if (AR == 0 \& WW > 0)
      okToWrite.signal();
    lock.Release();
```

- R1 finishes (W1, R3 waiting)
- AR = 0, WR = 0, AW = 0, WW = 0

AccessDbase(ReadOnly);

```
lock.Acquire();
AR--;
if (AR == 0 && WW > 0)
    okToWrite.signal();
lock.Release();
```

- R1 finishes (W1, R3 waiting)
- AR = 0, WR = 0, AW = 0, WW = 0

```
Reader()
    lock.Acquire();
    while ((AW + WW) > 0) \{ // \text{ Is it safe to read} \}
      WR++;
                                 // No. Writers exist
      okToRead.wait(&lock); // Sleep on cond var
WR--; // No longer waiting
    AR++;
                                 // Now we are active!
    lock.release();
    AccessDbase(ReadOnly);
    lock.Acquire();
    AK--;
    if (AR == 0 \& WW > 0)
       okToWrite.signal();
    lock.Release();
```

- R1 finishes (W1, R3 waiting)
- AR = 0, WR = 0, AW = 0, WW = 0

```
Reader()
    lock.Acquire();
    while ((AW + WW) > 0) \{ // \text{ Is it safe to read} \}
       WR++;
                                 // No. Writers exist
      okToRead.wait(&lock); // Sleep on cond var
WR--; // No longer waiting
    AR++;
                                 // Now we are active!
    lock.release();
    AccessDbase(ReadOnly);
    lock.Acquire();
    AR - -;
    if (AR == 0 \& WW > 0)
       okToWrite.signal();
    lock.Release();
                             DONE!
```

```
Writer()
Reader() {
                                    // check into system
lock.Acquire();
    // check into system
    lock.Acquire();
                                    while ((AW + AR) > 0) {
    while ((AW + WW) > 0) {
                                       WW++ 3
       WR++;
                                       okToWrite.wait(&lock);
       okToRead.wait(&lock);
                                       WW - - ;
       WR - -;
                                    AW++;
                                    lock.release();
    AR++;
    lock.release();
                                    // read/write access
                                    AccessDbase(ReadWrite);
                   What if we
    // read-only
                   remove this
    AccessDbase
                                     // check out of system
                   line?
                                    lock.Acquire();
                                    ÀW-
if
    // check out
                                        (\dot{W}W > 0)
    lock.Acquire 🗸
                                      okToWrite.signal();
else_if (WR > 0) {
    AR - - ;
                                       okToRead.broadcast();
       (AR == 0 && WW >
       okToWrite.signal();
                                     lock.Release();
    lock.Release();
```

```
Writer()
Reader() {
                                    // check into system
lock.Acquire();
    // check into system
    lock.Acquire();
                                    while ((AW + AR) > 0) {
    while ((AW + WW) > 0) {
                                       WW++ 3
       WR++;
                                       okToWrite.wait(&lock);
       okToRead.wait(&lock);
                                       WW - - ;
       WR - -;
                                    AW++;
                                    lock.release();
    AR++;
    lock.release();
                                    // read/write access
                                    AccessDbase(ReadWrite);
    // read-only
    AccessDbase
                   What if we turn
                                     / check out of system
                   signal to
                                    lock.Acquire();
                                    AŴ-
if
                  broadcast?
    // check out
                                        (\dot{W}W > 0)
    lock.Acquire
                                      okToWrite.signal();
else_if (WR > 0) {
    AR--;
                                       okToRead.broadcast();
    if (AR == 0 \& \& M > 0)
       okToWrite.broadcast();
                                    lock.Release();
    lock.Release();
```

```
Reader() {
                                 Writer()
                                      // check into system
lock.Acquire();
    // check into system
    lock.Acquire();
                                      while ((AW + AR) > 0) {
    while ((AW + WW) > 0) {
                                         WW++;
       WR++;
                                         okContinue.wait(&lock);
       okContinue.wait(&lock);
                                         WW - - :
       WR - -;
                                      AW++;
                                      lock.release();
    AR++;
    lock.release();
                                      // read/write access
AccessDbase(ReadWrite);
     // read-only access
    AccessDbase(ReadOnly);
                                       // check out of system
                                       lock.Acquire();
                                      AŴ-
if
     // check out of system
                                          (\dot{W}W > 0)
     lock.Acquire();
                                        okContinue.signal();
else if (WR > 0) {
okContinue.broadcast();
    AR--;
    if (AR == 0 \&\& WW > 0)
       okContinue.signal();
                                       lock.Release();
     lock.Release();
  }
```

What if we turn okToWrite and okToRead into okContinue?

Reader() { wri // check into system lock.Acquire();	<pre>ter() { // check into system lock.Acquire();</pre>
<pre>while ((AW + WW) > 0) { WR++; okContinue.wait(&lock); WD</pre>	<pre>while ((AW + AR) > 0) { WW++; okContinue.wait(&lock); WW; }</pre>
WR; } AR++; lock.release();	AW++; lock.release();
<pre>// read-only access AccessDbase(ReadOnly);</pre>	<pre>// read/write access AccessDbase(ReadWrite); // check out of system</pre>
<pre>// check out of system lock.Acquire(); AR; if (AR == 0 && WW > 0) okContinue.signal(); lock.Release();</pre>	<pre>lock.Acquire(); AW; if (WW > 0){ okContinue.signal(); } else if (WR > 0) { okContinue.broadcast(); } lock.Release();</pre>
• B1 arrives	

R1 arrives

• W1, R2 arrive while R1 still reading → W1 and R2 wait for R1 to finish
• Assume R1's signal is delivered to R2 (not W1)

```
Reader() {
                                Writer()
                                     // check into system
lock.Acquire();
    // check into system
    lock.Acquire();
                                     while ((AW + AR) > 0) {
    while ((AW + WW) > 0) {
                                        WW++ 3
       WR++;
                                        okContinue.wait(&lock);
       okContinue.wait(&lock);
                                        WW - - ;
       WR - -;
                                     AW++;
                                     lock.release();
    AR++;
    lock.release();
                                     // read/write access
                                     AccessDbase(ReadWrite);
    // read-only access
    AccessDbase(ReadOnly);
                                     // check out of system
                                     lock.Acquire();
                                     AŴ-
if
    // check out of system
                                         (\dot{W}W > 0)
    lock.Acquire();
                                       okContinue.signal();
else if (WR > 0) {
okContinue.broadcast();
    AR--;
    if (AR == 0 \&\& WW > 0)
       okContinue.broadcast();
                                     lock.Release();
    lock.Release();_
                             Need to change to broadcast!
```

```
Mengwei Xu @ BUPT Fall 2022
```



Implementing RWLock

• Let's wrap the code into a RWLock class

RWLock* rwlock;

rwlock->startRead();
// Read shared data
rwlock->doneRead();

rwlock->startWrite();
// Write shared data
rwlock->startRead();

Implementing RWLock

class RWLock {
 Lock lock;
 CV canRead;
 CV canWrite;
 int AR, AW, WR, WW;
}

```
void RWLock::startRead() {
   lock.acquire();
   WR ++;
   while ((AW + WW > 0)) {
      canRead.Wait(&lock);
   }
   WR --;
   AR ++;
   lock.release();
}
```

```
void RWLock::doneRead() {
   lock.acquire();
   AR --;
   if ((AR == 0) && (WW > 0)) {
      canWrite.signal();
   }
   lock.release();
}
```





```
class RWLock {
  Lock lock;
  CV canRead;
  CV canWrite;
  int AR, AW, WR, WW;
}
```

```
void RWLock::startWrite() {
   lock.acquire();
   WW ++;
   while ((AW + AR > 0)) {
      canWrite.Wait(&lock);
   }
   WW --;
   AW ++;
   lock.release();
}
```

```
void RWLock::doneWrite() {
  lock.acquire();
  AW --;
  assert(AW == 0);
  if (WW > 0) {
    canWrite.signal();
  else {
    canRead.broadcast();
  lock.release();
}
```

Goals for Today



- Readers/Writers Lock
- Deadlock

Deadlock



- Deadlock (死锁): a cycle of waiting among a set of threads, where each thread waits for some other thread in the cycle to take some action.
- A simple case: mutually recursive locking

// Thread A	// Thread B
-------------	-------------

lock1.acquire(); lock2.acquire(); lock2.release(); lock1.release(); lock2.acquire(); lock1.acquire(); lock1.release(); lock2.release();

Deadlock



- Deadlock (死锁): a cycle of waiting among a set of threads, where each thread waits for some other thread in the cycle to take some action.
- Another example with 2 locks and 1 condition variable

```
// Thread A
lock1.acquire();
lock2.acquire();
while (need to wait) {
   cv.wait(&lock2);
}
lock2.release();
lock1.release();
```

```
// Thread B
```

```
lock1.acquire();
lock2.acquire();
cv.signal();
lock2.release();
lock1.release();
```

Deadlock



- Deadlock (死锁): a cycle of waiting among a set of threads, where each thread waits for some other thread in the cycle to take some action.
- Another example with 2 locks and 1 condition variable

```
// Thread A // Thread B
```

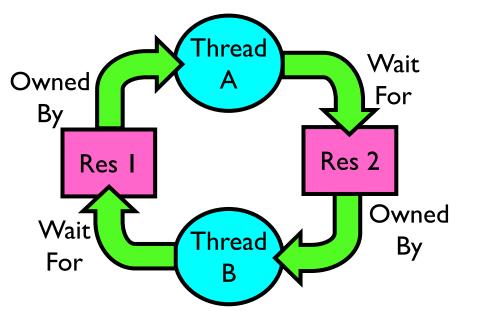
```
lock1.acquire(); loc
lock2.acquire(); loc
while (need to wait) {
    cv.wait(&lock2); loc
} lock2.release();
lock1.release(); Any deadlock?
```

```
lock1.acquire();
lock2.acquire();
cv.signal();
lock2.release();
lock1.release();
```



Starvation vs Deadlock

- Starvation vs. Deadlock
 - Starvation: thread waits indefinitely
 - Example, low-priority thread waiting for resources constantly in use by high-priority threads
 - Deadlock: circular waiting for resources
 Thread A owns Res I and is waiting for Res 2 Thread B owns Res 2 and is waiting for Res I
 - Deadlock ⇒ Starvation but not vice versa
 □ Starvation can end (but doesn't have to)
 □ Deadlock can't end without external intervention





Bridge Crossing Example

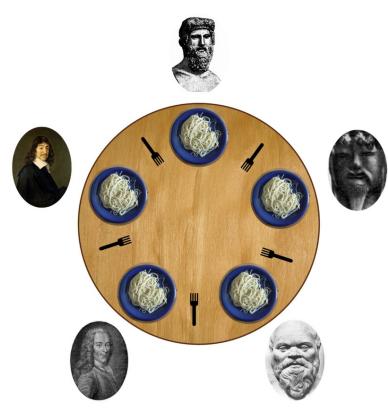
- Each segment of road can be viewed as a resource
 - Car must own the segment under them
 - Must acquire segment that they are moving into
- For bridge: must acquire both halves
 - Traffic only in one direction at a time
 - Problem occurs when two cars in opposite directions on bridge: each acquires one segment and needs next
- If a deadlock occurs, it can be resolved if one car backs up (preempt resources and rollback)
 - Several cars may have to be backed up
- Starvation is possible
 - East-going traffic really fast \Rightarrow no one goes west





Dining Philosophers Problem

- Dining Philosophers Problem (哲学家进餐问题)
 - For example: 5 philosophers, 5 plate, and 5 chopsticks
 - When a philosopher thinking, he holds nothing
 - When a philosopher wants to eat, he first picks up the left chopstick, and then the right chopstick. After eating, he puts down both chopsticks.
 - Stuck when everyone holds the left chopstick
 - A general case of mutually recursive locking





Conditions for Deadlock

• Deadlock not always deterministic – Example 2 mutexes:

<u>Thread</u> B
y.P();
x.P();
x.V();
y.V();

- Deadlock won't always happen with this code
 - □ Have to have exactly the right timing ("wrong" timing?)
 - So you release a piece of software, and you tested it, and there it is, controlling a nuclear power plant...
- Deadlocks occur with multiple resources
 - Means you can't decompose the problem
 - Can't solve deadlock for each resource independently
- Example: System with 2 disk drives and two threads
 - Each thread needs 2 disk drives to function
 - Each thread gets one disk and waits for another one



Four requirements for Deadlock

• Mutual exclusion

- Only one thread at a time can use a resource.
- Hold and wait
 - Thread holding at least one resource is waiting to acquire additional resources held by other threads
- No preemption
 - Resources are released only voluntarily by the thread holding the resource, after thread is finished with it
- Circular wait
 - There exists a set $\{T_1, \ldots, T_n\}$ of waiting threads
 - $\Box T_i$ is waiting for a resource that is held by T_{i+1}



Four requirements for Deadlock

• Mutual exclusion

- Only one thread at a time can use a resource.
- Each chopstick can be held by a single philosopher at a time
- Hold and wait
 - Thread holding at least one resource is waiting to acquire additional resources held by other threads
 - When a philosopher needs to wait for a chopstick, he continues to hold onto any chopsticks he has already picked up
- No preemption
 - Resources are released only voluntarily by the thread holding the resource, after thread is finished with it
 - Once a philosopher picks up a chopstick, he does not release it until he is done eating.
- Circular wait
 - There exists a set $\{T_1, \ldots, T_n\}$ of waiting threads
 - $\Box T_i$ is waiting for a resource that is held by T_{i+1}
 - Everyone is holding the left chopstick but waiting for the right one.



Methods for Handling Deadlocks

- Allow system to enter deadlock and then recover
 - Requires deadlock detection algorithm
 - Some technique for forcibly preempting resources and/or terminating tasks
- Ensure that system will *never* enter a deadlock
 - Need to monitor all lock acquisitions
 - Selectively deny those that *might* lead to deadlock
- Ignore the problem and pretend that deadlocks never occur in the system
 - Used by most operating systems, including UNIX



Preventing Deadlocks

- I. No circular wait
- 2. No hold-and-wait
- 3. No mutual exclusion
- 4. Smart scheduling
 - banking algorithm



I. No circular wait

- 2. No hold-and-wait
- 3. No mutual exclusion
- 4. Smart scheduling
 - banking algorithm



Removing Circular Wait

* Lock ordering:

->i rwsem

->mmap lock

->mmap lock

->i rwsem

sb_lock
->i pages lock

->i mmap rwsem

->anon vma.lock

->swap_lock

->private lock

->i_pages lock

->private_lock

->i_pages lock

bdi.wb->list_lock
->inode->i lock

->memcg->move_lock

bdi.wb->list lock

->inode->i_lock

->private lock

->lruvec->lru_lock
->lruvec->lru_lock

->anon vma.lock

->page_table_lock or pte_lock

->page_table_lock or pte_lock

*

*

*

*

*

*

* */ ->i_mmap_rwsem
 ->private_lock

->swap lock

->invalidate_lock

->invalidate_lock

->lock_page

->mmap_lock
bdi->wb.list lock

->i_mmap_rwsem

->i_mmap_rwsem

->i_pages lock

->i pages lock

(truncate pagecache)

->page_table_lock or pte_lock (various, mainly in memory.c)

(filemap_fault)

(generic_perform_write)

(fs/fs-writeback.c)

(try_to_unmap_one)

(try to unmap one)

(try_to_unmap_one)

(vma merge)

(___sync_single_inode)

__free_pte->block_dirty_folio)

(acquired by fs in truncate path)

(arch-dependent flush dcache mmap lock)

(filemap_fault, access_process_vm)

(fault in readable->do page fault)

(anon_vma_prepare and various)

(follow_page_mask->mark_page_accessed)

(folio_remove_rmap_pte->set_page_dirty)

(folio remove rmap pte->set page dirty)

(folio_remove_rmap_pte->set_page_dirty)

(folio_remove_rmap_pte->set_page_dirty)
(folio_remove_rmap_pte->folio_memcg_lock)

(zap_pte_range->set_page_dirty) (zap_pte_ran<u>ge->set_page_dirty)</u>

(zap pte range->block dirty folio)

(check_pte_range->folio_isolate_lru)

(truncate->unmap_mapping_range)

(exclusive swap page, others)

- Just make sure all locks acquired in the same order!
 - Total ordering
 - Partial ordering
 - An excellent example: memory mapping code in Linux

https://github.com/torvalds/linux/blob/master/mm/filemap.c



Removing Circular Wait

- Just make sure all locks acquired in the same order!
 - Total ordering
 - Partial ordering

func(mutex_t *ml, mutex_t *m2)

How to guarantee the ordering in func? Think about this case: In Thread A: func(L1, L2) In Thread B: func(L2, L1)



- Just make sure all locks acquired in the same order!
 - Total ordering
 - Partial ordering
- Enforce lock ordering by lock address

func(mutex_t *ml, mutex_t *m2)

How to guarantee the ordering in func? Think about this case: In Thread A: func(L1, L2) In Thread B: func(L2, L1)

```
if (m1 > m2) { // grab in high-to-low address order
   pthread_mutex_lock(m1);
   pthread_mutex_lock(m2);
} else {
   pthread_mutex_lock(m2);
   pthread_mutex_lock(m1);
}
// Code assumes that m1 != m2 (not the same lock)
```





I. No circular wait

- Cons: needs careful design and programming from developers.
- 2. No hold-and-wait
- 3. No mutual exclusion
- 4. Smart scheduling
 - banking algorithm





- I. No circular wait
- 2. No hold-and-wait
- 3. No mutual exclusion
- 4. Smart scheduling
 - banking algorithm



Preventing Hold and Wait

• Just use another lock to lock the locks

```
pthread_mutex_lock(prevention); // begin acquisition
2 pthread_mutex_lock(L1);
3 pthread_mutex_lock(L2);
4 ...
5 pthread_mutex_uplock(prevention): // ord
```

5 pthread_mutex_unlock(prevention); // end

Preventing Deadlocks



- I. No circular wait
- 2. No hold-and-wait
 - Cons: must know which locks will be used beforehand; concurrency decreased.
- 3. No mutual exclusion
- 4. Smart scheduling
 - banking algorithm





- I. No circular wait
- 2. No hold-and-wait
- 3. No mutual exclusion
- 4. Smart scheduling
 - banking algorithm



Preventing Mutual Exclusion

• Design lock-free (or wait-free) data structures and algorithms using powerful hardware instructions

```
int CompareAndSwap(int *address, int expected,
int new) {
    if (*address == expected) {
        *address = new;
        return 1; // success
    }
    return 0; // failure
}
```



Preventing Mutual Exclusion

• Using **CompareAndSwap** to implement "increment a value by n".

```
void AtomicIncrement(int *value, int n) {
    do {
        int old = *value;
        } while (CompareAndSwap(value, old, old + n)==0);
}
```



• Using **CompareAndSwap** to implement "insert an element to a list head".

```
// without deadlock prevention
void insert(int value) {
   node_t *n = malloc(sizeof(node_t));
   assert(n != NULL);
   n->value = value;
   n->next = head;
   head = n;
```



• Using **CompareAndSwap** to implement "insert an element to a list head".

```
// with deadlock prevention
void insert(int value) {
  node t *n = malloc(sizeof(node t));
  assert(n != NULL);
  n->value = value;
  do {
    n \rightarrow next = head;
  } while (CompareAndSwap(&head, n->next, n) == 0);
```





- I. No circular wait
- 2. No hold-and-wait
- 3. No mutual exclusion
 - Cons: too complicated; hardware support needed (possibly performance degradation).
- 4. Smart scheduling
 - banking algorithm





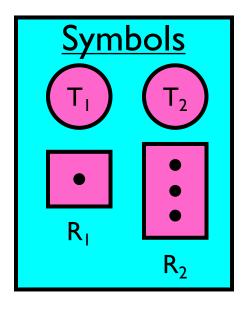
- I. No circular wait
- 2. No hold-and-wait
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- 4. Smart scheduling
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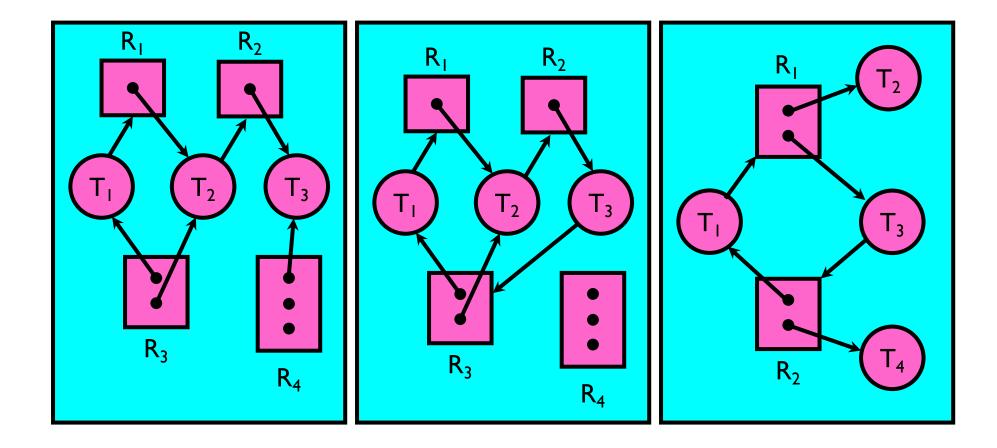
Resource-Allocation Graph

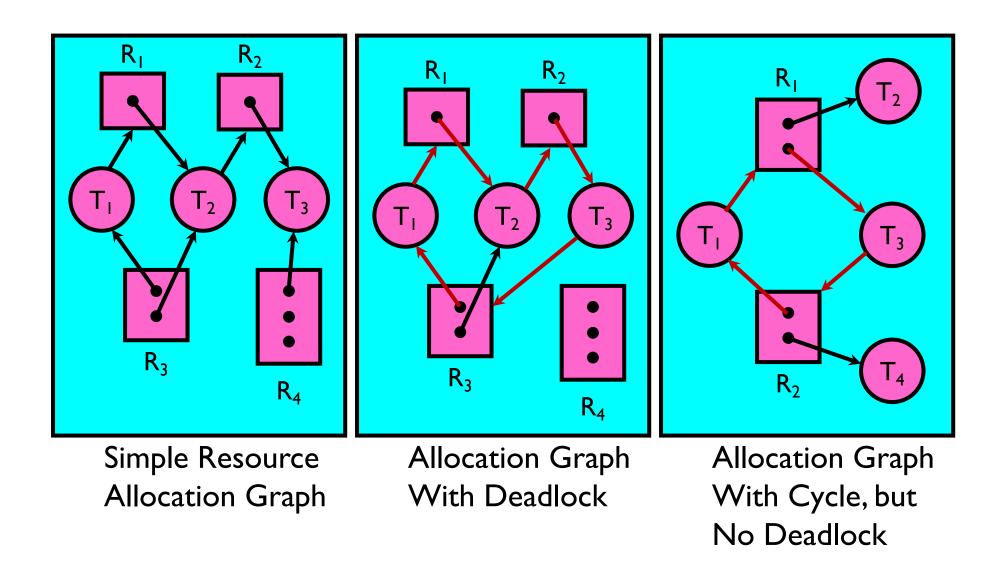
- System Model
 - A set of Threads T_1, T_2, \ldots, T_n
 - Resource types R₁, R₂, . . ., R_m CPU cycles, memory space, I/O devices
 - Each resource type R_i has W_i instances
 - Each thread utilizes a resource as follows:

 Request() / Use() / Release()
- Resource-Allocation Graph:
 - V is partitioned into two types:
 - $\Box T = \{T_1, T_2, \dots, T_n\}$, the set threads in the system.
 - $\Box R = \{R_1, R_2, ..., R_m\}$, the set of resource types in system
 - request edge directed edge $T_1 \rightarrow R_i$
 - assignment edge directed edge $R_j \rightarrow T_i$









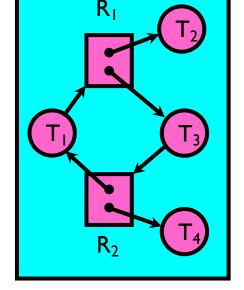


Deadlock Detection Algorithm

- Only one of each type of resource \Rightarrow look for loops
- More General Deadlock Detection Algorithm
 - Let [X] represent an m-ary vector of non-negative integers (quantities of resources of each type):
 [FreeResources]: Current free resources each type Current requests from thread X Current resources held by thread X
 - See if tasks can eventually terminate on their own

```
[Avail] = [FreeResources]
Add all nodes to UNFINISHED
do {
```

```
done = true
Foreach node in UNFINISHED {
    if ([Request<sub>node</sub>] <= [Avail]) {
        remove node from UNFINISHED
        [Avail] = [Avail] + [Alloc<sub>node</sub>]
        done = false
        }
    }
} until(done)
```



- Nodes left in **UNFINISHED** \Rightarrow deadlocked

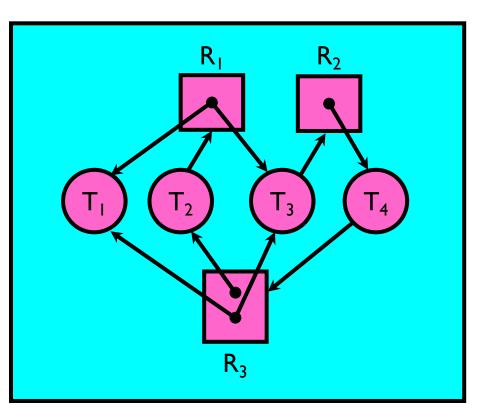


- Terminate thread, force it to give up resources
 - In Bridge example, Godzilla picks up a car, hurls it into the river. Deadlock solved!
 - But, not always possible killing a thread holding a mutex leaves world inconsistent
- Preempt resources without killing off thread
 - Take away resources from thread temporarily
 - Doesn't always fit with semantics of computation
- Roll back actions of deadlocked threads
 - Hit the rewind button, pretend last few minutes never happened
 - For bridge example, make one car roll backwards (may require others behind him)
 - Common technique in databases (transactions)
 - Of course, if you restart in exactly the same way, may reenter deadlock once again
- Many operating systems use other options



Resource Requests over Time

- Applications usually don't know exactly when/what they're going to request
- Resources are taken/released over time





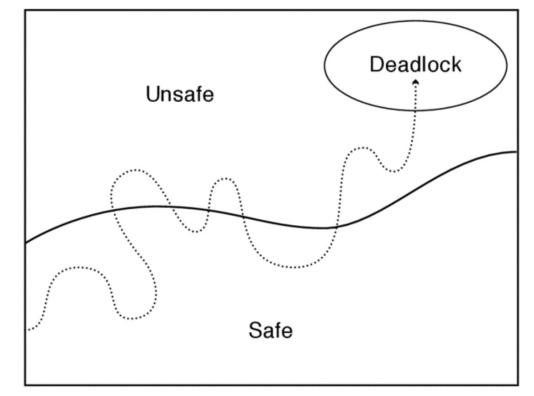
- What if you don't know the order/amount of requests ahead of time?
- Must assume some worst-case "max" resource needed by each process
- Toward right idea:
 - State maximum resource needs in advance
 - Allow particular thread to proceed if:
 - (available resources #requested) \geq
 - max remaining that might be needed by any thread
 - Invariant: At all times, every request would succeed
 - Really conservative! Let's do something better.



- Invariant: At all times, there exists some order of requests that would succeed.
- Key ideas
 - A thread states its maximum resource requirements, but acquires and releases resources incrementally as the thread executes.
 - The runtime system delays granting some requests to ensure that the system never deadlocks.

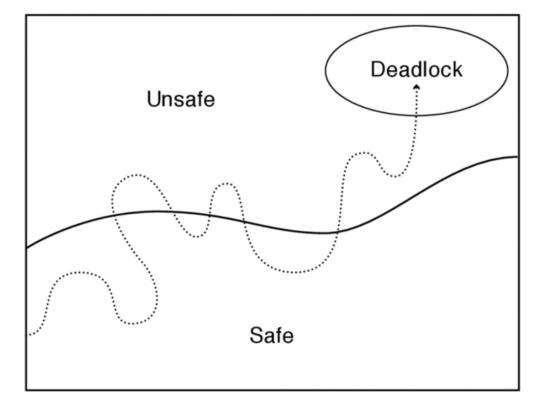


- Safe state: for any possible <u>sequence of</u> <u>resource requests</u>, there is at least one safe <u>sequence of processing</u> the requests that eventually succeeds in granting all pending and future requests.
- Unsafe state: there is at least one sequence of future resource requests that leads to deadlock no matter what processing order is tried.
- **Deadlocked state:** the system has at least one deadlock.



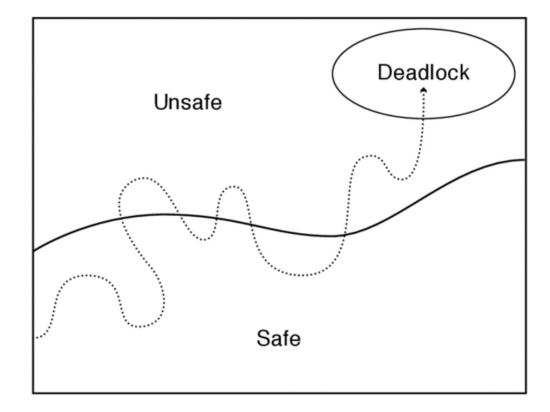


- Safe state: for any possible <u>sequence of</u> <u>resource requests</u>, there is at least one safe <u>sequence of processing</u> the requests that eventually succeeds in granting all pending and future requests.
 - A system in a safe state controls its own destiny: for any workload, it can avoid deadlock by delaying the processing of some requests.





- Unsafe state: there is at least one sequence of future resource requests that leads to deadlock no matter what processing order is tried.
 - An unsafe state does not always lead to deadlock
 - However, as long as the system remains in an unsafe state, a bad workload or unlucky scheduling of requests can force it to deadlock.





- Invariant: At all times, there exists some order of requests that would succeed.
- The banker's algorithm delays any request that takes it from a safe to an unsafe state.



- Delay a request that takes us into unsafe state.
- How to implement this?
 - Allocate resources dynamically
 - Evaluate each request and grant if some ordering of threads is still deadlock free afterward
 - Use deadlock detection algorithm presented earlier:

BUT: Assume each process needs ''max'' resources to finish

```
[Avail] = [FreeResources]
Add all nodes to UNFINISHED
do {
    done = true
    Foreach node in UNFINISHED {
        if ([Request<sub>node</sub>] <= [Avail]) {
            remove node from UNFINISHED
            [Avail] = [Avail] + [Alloc<sub>node</sub>]
            done = false
        }
    }
    } until(done)
```



- Delay a request that takes us into unsafe state.
- How to implement this?
 - Allocate resources dynamically
 - Evaluate each request and grant if some ordering of threads is still deadlock free afterward
 - Use deadlock detection algorithm presented earlier:

BUT: Assume each process needs ''max'' resources to finish

[Avail] = [FreeResources] Each process might Add all nodes to UNFINISHED need"max" resources do { in order to finish done = true Foreach node in UNFINISHED { if ([Max_{node}]-[Alloc_{node}] <= [Avail]) {</pre> remove node from UNFINISHED [Avail] = [Avail] + [Alloc_{node}] done = false} until(done)



- Delay a request that takes us into unsafe state.
- How to implement this?
 - Allocate resources dynamically
 - Evaluate each request and grant if some ordering of threads is still deadlock free afterward
 - Use deadlock detection algorithm presented earlier:
 BUT: Assume each process needs "max" resources to finish
- Keeps system in a "SAFE" state, i.e. there exists a sequence $\{T_1, T_2, ..., T_n\}$ with T_1 requesting all remaining resources, finishing, then T_2 requesting all remaining resources, etc..
- vs. "Require all before starting", the Banker's algorithm allows the sum of maximum resource needs of all current threads to be greater than total resources



- EXAMPLE: Page allocation with the Banker's Algorithm.
 - Suppose we have a system with 8 pages of memory and three processes: A, B, and C, which need 4, 5, and 5 pages to complete, respectively.
- They take turns requesting one page each, and the system grants requests in order



- EXAMPLE: Page allocation with the Banker's Algorithm.
 - Suppose we have a system with 8 pages of memory and three processes: A, B, and C, which need 4, 5, and 5 pages to complete, respectively.
- They take turns requesting one page each, and the system grants requests in order

Process	Allocation								Oops! Deadlock!				
А	0	1	1	1	2	2	2	3	3	3	wait	wait	
В	0	0	1	1	1	2	2	2	3	3	3	wait	
С	0	0	0	1	1	1	2	2	2	wait	wait	wait	
Total	0	1	2	3	4	5	6	7	8	8	8	8	



• EXAMPLE: Page allocation with the Banker's Algorithm.

- Suppose we have a system with 8 pages of memory and three processes: A, B, and C, which need 4, 5, and 5 pages to complete, respectively.
- What if we use banker's algorithm?

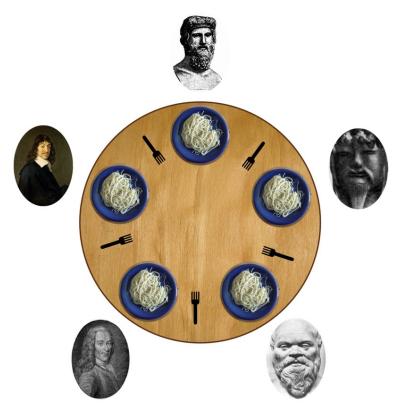
Process Allocation 3 0 0 0 0 ()1 **2** 2 2 **3** 3 4 0 0 0 Α () 5 Β 1 1 2 2 2 wait wait wait wait 3 4 4 0 0 0 0 0 wait wait wait 3 3 wait wait **5 0** 0 0 1 1 1 2 2 2 4 ()0 1 2 3 4 5 6 7 7 8 4 6 7 7 8 Total 7 5 4 0

Tasks successfully finished



Banker's Algorithm Example

- Banker's algorithm with dining philosophers
 - "Safe" (won't cause deadlock) if when try to grab chopstick either:
 Not last chopstick
 - Is last chopstick but someone will have two afterwards
 - What if k-handed philosopher? Don't allow if:
 It's the last one, no one would have k
 It's 2nd to last, and no one would have k-1
 It's 3rd to last, and no one would have k-2
 ...







- I. No circular wait
- 2. No hold-and-wait
- 3. No mutual exclusion
- 4. Smart scheduling
 - banking algorithm
 - Cons: must know the entire set of tasks and their resource demands beforehand; concurrency decreased.
 - Only used in limited scenarios such as embedded system.



Techniques for Preventing Deadlock

- Infinite resources
 - Include enough resources so that no one ever runs out of resources. Doesn't have to be infinite, just large
 - Give illusion of infinite resources (e.g. virtual memory)
- No Sharing of resources (totally independent threads)
 - Often true (most things don't depend on each other)
 - Not very realistic in general (can't guarantee)



Deadlock Prevention – The Reality

- Deadlock Prevention is HARD
 - How many resources will each thread need?
 - How many total resources are there?
- Also Slow/Impractical
 - Matrix of resources/requirements could be big and dynamic
 - Re-evaluate on every request (even for small/non-contended)
 - Banker's algorithm assumes everyone asks for max
- REALITY
 - Most OSes don't bother
 - Programmers job to write deadlock-free programs (e.g. by ordering all resource requests).



- Modify our RWLock implementation to use only one condition variable
- Implement Banker's Algorithm
 - Input-1: task number N, resource type number M;
 - Input-2: resource amount: for each type: $R_{\rm i}$ where i=1-M
 - Input-3: MAX resource for each task $\langle T_{i,j} \rangle$ where i=1-N and j=1-M;
 - Input-4: Sequence of resource request <R_{i,j}> where i=1-N and j=1-M
 You can define your own way to generate this sequence
 - Test your algorithm with a large number of random sequences of resource request. Make sure deadlock never happens!